

# A numeric-symbolic algorithm for computing the Liouvillian solutions of linear differential equations and systems

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## Abstract

We give an algorithm for deciding if an explicitable higher-order system of linear differential equations over the complex rational functions, given symbolically, admits non-null Liouvillian solutions, computing one in the positive case, by numeric-symbolic methods in the sense of J. van der Hoeven.

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# What differential equations?

We work with explicitable higher-order systems of linear homogeneous differential equations over the complex rational functions.

## Explicitable higher-order systems of linear differential equations

A higher-order system of linear homogeneous differential equations

$$A_r(x)y^{(r)} + A_{r-1}(x)y^{(r-1)} + \cdots + A_0(x)y = 0,$$

with  $A_0(x), A_1(x), \dots, A_r(x)$  matrices  $n \times n$ , is **explicitable** if  $\det A_r(x) \neq 0$ .

“Explicitable” because they can be made explicit in  $y^{(r)}$ .

This deals with both scalar linear differential equations (for  $n = 1$ ) and first-order linear systems of differential equations (for  $r = 1$ ) at once.

The matrices  $A_0(x), A_1(x), \dots, A_r(x)$  consist of complex rational functions symbolically given.

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# What kind of solutions?

## Liouvillian solutions

A function is **Liouvillian** if it is built up by the use of

- rational operations
- derivatives
- exponentials
- quadratures
- solution of polynomials

over the rational functions.

# By what methods?

I speak of **numeric-symbolic** methods in the sense of J. van der Hoeven's *Around the numeric-symbolic computation of differential Galois groups* (JSC 2007), where he proposes an algorithm for decomposing differential operators.

## Global structure

- symbolic preprocess
- numerical computation at a given precision
  - it may give false positives, but not false negatives
  - the result is correct for precision fine enough
- symbolic reconstruction of the candidate solution and symbolic testing
  - if the test successes, the candidate solution is true
  - if the test fails, we repeat the numerical computation at finer precision

These properties of the numerical step grant that the procedure terminates

- if the answer is positive, with a true solution at the symbolic step
- if the answer is negative, with a true negative at the numerical step

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# The solutions we look for

Applying the Cyclic Vector Lemma, we can extend the following theorem of Singer to systems.

## Singer's theorem

There exists an arithmetic function  $l : \mathbb{N} \rightarrow \mathbb{N}$  such that, if a scalar differential equations of order  $r$  has a non-null Liouvillian solution, then there exists a solution  $y \neq 0$  such that  $y'/y$  is algebraic of degree  $l(r)$  at most.

I called such solutions **Singerian solutions**.

## Galoisian characterization

If  $G$  is the differential Galois group of an  $n \times n$  system of order  $r$ , and  $G^\circ$  its identity component, a solution  $y \neq 0$  is Singerian if and only if the line  $\mathbb{C}y$  is invariant by  $G^\circ$  and its orbit by the action of  $G$  has length  $l(nr)$  at most.

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## Form of the Singerian solutions

For any Singerian solution  $\mathbf{y}$ , there exist an integer  $p > 0$ ,  $\alpha \in \mathbb{C}$ , a polynomial  $q$  with  $q(0) = 0$  and convergent series  $f_1, f_2, \dots, f_n$  such that  $\mathbf{y} = \exp(q(x^{-1/p})) x^\alpha (f_1(x^{1/p}), f_2(x^{1/p}), \dots, f_n(x^{1/p}))^\top$ .

Compared with Fabry-Hukuhara-Turrittin form, Singerian solutions are free of logarithms and divergence, so they present a special behavior under Ramis generators of the differential Galois group.

## Ramis generators of the local Galois group

- monodromy
- Stokes automorphisms
- exponential torus

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## Ramis generators of the local Galois group

- monodromy
- Stokes automorphisms (trivial)
- exponential torus (scalar)

# Computation of Ramis generators

- Centered at a singularity, we can compute symbolically the ramification index  $p$  and the admissible pairs  $(q, \alpha)$  of the Fabry-Hukuhara-Turrittin formal solutions.
- For each pair  $(q, \alpha)$ , we can compute numerically the solutions in  $\exp(q(x^{-1/p})) x^\alpha \mathbb{C}\{x^{1/p}\}$ . We need only numerical analytic continuation and linear algebra.
- This structure (a union of vector subspaces whose sum is direct) contains the Singerian solutions, can be moved (by numerical analytic continuation) to a common point for all the singularities and (by numerical linear algebra) can be intersected getting another structure of this kind.
- By numerical analytic continuation we can compute the generators of the monodromy group.

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For these computations of the Ramis generators, we will not use ordinary numerics, but effective numerics.

## Effective complex numbers

A complex number  $a$  is **effective** if it is endowed with an algorithm  $f : \mathbb{N}^{2\mathbb{Z}} \rightarrow (\mathbb{Z} + i\mathbb{Z})^{2\mathbb{Z}}$  such that  $|f(\varepsilon) - a| < \varepsilon$  for any  $\varepsilon \in \mathbb{N}^{2\mathbb{Z}}$ .

- The rational operations among effective complex numbers are effective, provided we have a lower bound of the denominator.
- J. van der Hoeven (1999) develops the numerical analytic continuation of the solutions of a linear differential equation with polynomial coefficients, which can be extended to explicitable systems.
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- The numerical version of Gaussian elimination may deem zero a non-zero row/column, and thus underestimate the rank, but it cannot overestimate the rank.
- Nevertheless, for  $\text{tol}$  small enough, this approximate zero-test works correctly.
- The algorithm of this work is devised in such a way that the space of Singerian solutions may be overestimated, but never underestimated.
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# Eurymeric closure of the Galois group

- H. Derksen (2005) and J. van der Hoeven (2007) devised an algorithm for computing the algebraic group generated by a finite family of matrices, but it relies on some exact computations which would require infinite time in effective numerics.
- In order to avoid this impossibility, we define the **eurymeric closure** of a linear algebraic group, which can be computed in effective numerics up to testing if a number is zero or a root of unity.
- What we can effectively compute is a truncation of the eurymeric closure, which is enough for the computation of Singerian solutions.

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# Sketch of the global algorithm

- 1 Compute the truncation of the eurymeric group  $G$  generated by the Ramis generators, on a space containing all the Singerian solutions, as the Lie algebra  $\mathfrak{g}$  and generators of  $G/G^\circ$ .
- 2 Choose a common eigenvector of  $\mathfrak{g}$  with the indications of my thesis and in such a determined way that the same Lie algebra yields always the same eigenvector.
  - If there is no common eigenvector, this proves that there is no non-null Liouvillian solution.
- 3 Construct the Darboux polynomial corresponding to the chosen eigenvector and reconstruct symbolically its coefficients.
- 4 Check if the reconstruction of the Darboux polynomial is an actual Darboux polynomial and if it satisfies the Brill equations.
  - In case of failure, we restart the numerical computation with finer precision, which will be explained later.

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# Symbolic reconstruction

- Given a rational function  $f(x)$  as an effective power series, we reconstruct symbolically the numerator and the denominator of  $f(x)$  by means of Padé approximation.
- We proved that the constants in the final result are algebraic over the constants of the original data.
- In order to reconstruct the minimal polynomial of such constants, J. van der Hoeven proposes using the LLL algorithm, and I added HJLS and PSLQ to the repertoire, whose terminations proofs I had to refine for effective numerics.

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# The main results of the work

Several steps of the algorithm require truncation parameters in order to keep the computations finite.

Giving a suitable meaning to “refining the precision” for all these truncation parameters together, we get the following result.

## The main theorem of the work

The main algorithm of the work terminates with a non-zero Liouvillian solution, if such a solution exists, or with the statement that zero is the only Liouvillian solution if this is the case.

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- The simplest non-trivial examples are second-order equations or systems, studied by Kovacic (1979).
- An interesting higher-order example can be built up as direct sum of second-order ones.
- If we do not know the coordinates that split the system as direct sum, we cannot use the techniques designed for second-order equations.
- So, we shall review how our algorithm works with some significant second-order equations.



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# Example: Euler equation

## Example (Euler equation)

The differential equation,

$$x^3 y'' + (x^2 + x)y' - y = 0,$$

has as a fundamental system of solutions

$$f = \exp\left(\frac{1}{x}\right) \quad \text{and} \quad \hat{g} = \sum_{n=0}^{\infty} (-1)^n n! x^{n+1}.$$

- This equation has two singularities (at the origin and at infinity) and hence one monodromy.
- The ramification index is 1, so the Singerian solutions must be invariant by the monodromy.
- If  $g$  is any sum of  $\hat{g}$ , we have that  $f$  is invariant by the monodromy and  $g$  is not.

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- The admissible pairs are  $\{q(t) = t, \alpha = 0\}$  and  $\{q(t) = 0, \alpha = 0\}$ , yielding  $\exp(q(x^{-1}))x^\alpha = f$  and  $\exp(q(x^{-1}))x^\alpha = 1$  respectively.
- Then we check if  $f^{-1}y$  or  $y$  annihilate  $y \mapsto \int_{\mathbb{C}^*} y(z) z^k dz$  for  $k \geq 0$ .
- All these integrals vanish for  $f^{-1}f = 1$ , but none of them does for  $f$ , so the only candidate space is  $\mathbb{C}f$  with  $q(t) = t$  and  $\alpha = 0$ .
- As  $\mathbb{C}f$  is invariant by the Galoisian action, it is a candidate Singerian orbit.
- Then we reconstruct symbolically the Darboux polynomial, getting that the candidate Singerian solution is  $\exp(1/x)$  and that it is indeed a solution.

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# Example: Airy equation

## Example (Airy equation)

The differential equation,

$$y'' = x y,$$

has as a fundamental system of solutions

$$h_{\pm} = \exp\left(\pm \frac{2}{3}x^{3/2}\right) x^{-1/4} \hat{\varphi}(\pm x^{-3/2}),$$

where  $\hat{\varphi}$  is a formal series with no null term.

- This equation has one singularity (at infinity) and hence no monodromy.
- We center the variable  $u = x^{-1}$  at infinity, where the ramification index is 4.
- The admissible pairs are  $\{q_{\pm}(t) = \pm \frac{2}{3}t^6, \alpha = \frac{1}{4}\}$ .

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Thank you for the attention

A numeric-symbolic algorithm  
for computing the Liouvillian solutions  
of linear differential equations and systems

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