

RESULTANTS AND SUBRESULTANTS THROUGH EVALUATION

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- ➊ Resultants and Subresultants: basics.
- ➋ Resultants and Subresultants in terms of roots.
- ➌ Resultants and Subresultants through evaluation.
- ➍ Resultants and Subresultants through evaluation
(the motivation).
- ➎ Conclusions and further work.

RESULTANTS AND SUBRESULTANTS

Resultant

$$P(x) = \sum_{i=0}^p a_i x^i$$

$$Q(x) = \sum_{i=0}^q b_i x^i$$

$$\text{Resultant}(P, Q) = \begin{vmatrix} a_p & \dots & a_0 & & \\ & \ddots & & \ddots & \\ & & a_p & \dots & a_0 \\ b_q & \dots & b_0 & & \\ & \ddots & & \ddots & \\ & & b_q & \dots & b_0 \end{vmatrix}$$

$P(x)$ and $Q(x)$ have a common root if and only if $\text{Resultant}(P, Q)=0$

Subresultants

$$\mathbf{Sylv}_i(P, Q) = \left\{ \begin{array}{cccccc} a_p & \dots & a_0 & & & \\ \ddots & & & \ddots & & \\ & a_p & \dots & a_0 & & \\ b_q & \dots & b_0 & & & \\ \ddots & & & \ddots & & \\ b_q & \dots & b_0 & & & \end{array} \right\} \begin{array}{l} p+q-i \\ q-i \\ p-i \end{array}$$

$$\mathbf{Sres}_i(P, Q) = \sum_{k=0}^i M_k x^k$$

$$P := a_4 x^4 + a_3 x^3 + a_2 x^2 + a_1 x + a_0$$

$$Q := b_3 x^3 + b_2 x^2 + b_1 x + b_0$$

$$M_0 := \begin{bmatrix} a_4 & a_3 & a_2 & a_1 & a_0 & 0 & 0 \\ 0 & a_4 & a_3 & a_2 & a_1 & a_0 & 0 \\ 0 & 0 & a_4 & a_3 & a_2 & a_1 & a_0 \\ b_3 & b_2 & b_1 & b_0 & 0 & 0 & 0 \\ 0 & b_3 & b_2 & b_1 & b_0 & 0 & 0 \\ 0 & 0 & b_3 & b_2 & b_1 & b_0 & 0 \\ 0 & 0 & 0 & b_3 & b_2 & b_1 & b_0 \end{bmatrix}$$

Resultant:=det(M₀)=Sres₀(P,Q)

$$M_1 := \begin{bmatrix} a_4 & a_3 & a_2 & a_1 & a_0 & 0 \\ 0 & a_4 & a_3 & a_2 & a_1 & a_0 \\ b_3 & b_2 & b_1 & b_0 & 0 & 0 \\ 0 & b_3 & b_2 & b_1 & b_0 & 0 \\ 0 & 0 & b_3 & b_2 & b_1 & b_0 \end{bmatrix}$$

Sres₁(P,Q):=det(M₁₁)x+det(M₁₀)

$$M_2 := \begin{bmatrix} a_4 & a_3 & a_2 & a_1 & a_0 \\ b_3 & b_2 & b_1 & b_0 & 0 \\ 0 & b_3 & b_2 & b_1 & b_0 \end{bmatrix}$$

Sres₂(P,Q):= det(M₂₂)x²+ det(M₂₁)x+ det(M₂₀)

$$P := a_4 x^4 + a_3 x^3 + a_2 x^2 + a_1 x + a_0$$

$$Q := b_3 x^3 + b_2 x^2 + b_1 x + b_0$$

$$M_0 := \begin{bmatrix} a_4 & a_3 & a_2 & a_1 & a_0 & 0 & 0 \\ 0 & a_4 & a_3 & a_2 & a_1 & a_0 & 0 \\ 0 & 0 & a_4 & a_3 & a_2 & a_1 & a_0 \\ b_3 & b_2 & b_1 & b_0 & 0 & 0 & 0 \\ 0 & b_3 & b_2 & b_1 & b_0 & 0 & 0 \\ 0 & 0 & b_3 & b_2 & b_1 & b_0 & 0 \\ 0 & 0 & 0 & b_3 & b_2 & b_1 & b_0 \end{bmatrix}$$

$sres_0(P,Q)$

Resultant:=det(M₀)=Sres₀(P,Q)

$$M_1 := \begin{bmatrix} a_4 & a_3 & a_2 & a_1 & a_0 & 0 \\ 0 & a_4 & a_3 & a_2 & a_1 & a_0 \\ b_3 & b_2 & b_1 & b_0 & 0 & 0 \\ 0 & b_3 & b_2 & b_1 & b_0 & 0 \\ 0 & 0 & b_3 & b_2 & b_1 & b_0 \end{bmatrix}$$

Sres₁(P,Q):=det(M₁₁)x+det(M₁₀)
sres₁(P,Q)

$$M_2 := \begin{bmatrix} a_4 & a_3 & a_2 & a_1 & a_0 \\ b_3 & b_2 & b_1 & b_0 & 0 \\ 0 & b_3 & b_2 & b_1 & b_0 \end{bmatrix}$$

sres₂(P,Q)

Sres₂(P,Q):= det(M₂₂)x²+ det(M₂₁)x+ det(M₂₀)

Subresultants

$$\text{Sres}_i(P, Q) = (-1)^{i(q-i+1)}$$

$$\left| \begin{array}{ccccccc} a_p & a_{p-1} & a_{p-2} & \dots & \dots & a_0 \\ \ddots & \ddots & \ddots & & & \ddots \\ & a_p & a_{p-1} & a_{p-2} & \dots & \dots & a_0 \\ & & & 1 & -x & & \\ b_q & b_{q-1} & b_{q-2} & \dots & \dots & \dots & b_0 \\ \ddots & \ddots & \ddots & & & & \ddots \\ & b_q & b_{q-1} & b_{q-2} & \dots & \dots & b_0 \end{array} \right| \quad \left. \begin{array}{l} p-i \\ i \\ q-i \end{array} \right\}$$

Subresultants

$$\gcd(P, Q) = \mathbf{Sres}_i(P, Q)$$

\iff

$$\mathbf{sres}_0(P, Q) = \mathbf{sres}_1(P, Q) = \cdots = \mathbf{sres}_{i-1}(P, Q) = 0, \mathbf{sres}_i(P, Q) \neq 0$$

Used in (avoid divisions: parameters !)

* Cylindrical Algebraic Decomposition

* Computer Aided Geometric Design

* Real Algebraic Geometry

*

Subresultants

$$S_{j+1} \rightarrow (\deg(S_{j+1}) = j + 1)$$

$$S_j \rightarrow (\deg(S_j) = k \leq j)$$

$$S_{j-1} \rightarrow 0$$

$$\vdots \qquad \vdots$$

$$S_{k+1} \rightarrow 0$$

$$S_k \rightarrow \left(\frac{\text{lcof}(S_j)}{R_{j+1}} \right)^{j-k} S_j$$

$$S_{k-1} \rightarrow \frac{\text{Prem}(S_{j+1}, S_j)}{(-R_{j+1})^{j-k+2}}$$

RESULTANTS & SUBRESULTANTS IN TERMS OF THE ROOTS

In terms of the roots: Resultant

$$P(x) = \sum_{i=0}^p a_i x^i = a_p \prod_{i=1}^p (x - \alpha_i) \quad Q(x) = \sum_{j=0}^q b_j x^j = b_q \prod_{j=1}^q (x - \beta_j)$$

In terms of the roots: Resultant

$$P(x) = \sum_{i=0}^p a_i x^i = a_p \prod_{i=1}^p (x - \alpha_i) \quad Q(x) = \sum_{j=0}^q b_j x^j = b_q \prod_{j=1}^q (x - \beta_j)$$

$$\text{Res}(P, Q) = a_p^q \prod_{i=1}^p Q(\alpha_i) = b_q^p \prod_{j=1}^q P(\beta_j) = a_p^q b_q^p \prod_{i=1}^p \prod_{j=1}^q (\alpha_i - \beta_j)$$

In terms of the roots: Subresultants

If $P(x)$ is monic and squarefree

$k \in \{0, \dots, \min(p, q) - 1\}$ and $N = \{1, \dots, p\}$,

$$P_I(x) = \prod_{i \in I} (x - \alpha_i)$$

$$\text{Sres}_k(P, Q) = \sum_{\substack{I \uplus J = N \\ |J|=k}} \frac{\text{res}(P_I, Q)}{\text{res}(P_I, P_J)} P_J(x) = \boxed{\sum_{\substack{I \uplus J = N \\ |J|=k}} \frac{\prod_{i \in I} Q(\alpha_i)}{\prod_{i \in I, j \in J} (\alpha_i - \alpha_j)} P_J(x)}$$

A. Lascoux, P. Pragacz: *Double Sylvester sums for subresultants and multi-Schur functions*. Journal of Symbolic Computation 35, 689-710, 2003.

C. D'Andrea, H. Hong, T. Krick, A. Szanto: *An elementary proof of Sylvester's double sums for subresultants*. Journal of Symbolic Computation 42, 290-297, 2007.

C. D'Andrea, H. Hong, T. Krick, A. Szanto: *Sylvester's double sums: The general case*. Journal of Symbolic Computation 44, 1164-1175, 2009.

M.-F. Roy, A. Szpirglas: *Sylvester double sums and subresultants*. Journal of Symbolic Computation 46, 385-395, 2011.

RESULTANTS & SUBRESULTANTS THROUGH EVALUATION (NOT IN THE ROOTS)

Through evaluation: Resultant (I)

The Bezoutian associated to $P(T)$ and $Q(T)$ is the symmetric matrix

$$\text{Bez}(P, Q) = \begin{bmatrix} c_{0,0} & \cdots & \cdots & c_{0,n-1} \\ \vdots & & & \vdots \\ c_{n-1,0} & \cdots & \cdots & c_{n-1,n-1} \end{bmatrix}$$

where the $c_{i,j}$ are defined by the Cayley quotient:

$$\frac{P(T)Q(Z) - P(Z)Q(T)}{T - Z} = \sum_{i,j=0}^{n-1} c_{i,j} T^i Z^j$$

Through evaluation: Resultant (I)

The Bezoutian associated to $P(T)$ and $Q(T)$ is the symmetric matrix

$$\text{Bez}(P, Q) = \begin{bmatrix} c_{0,0} & \cdots & \cdots & c_{0,n-1} \\ \vdots & & & \vdots \\ c_{n-1,0} & \cdots & \cdots & c_{n-1,n-1} \end{bmatrix}$$

where the $c_{i,j}$ are defined by the Cayley quotient:

$$\frac{P(T)Q(Z) - P(Z)Q(T)}{T - Z} = \sum_{i,j=0}^{n-1} c_{i,j} T^i Z^j$$

$$\det(\text{Bez}(P, Q)) = a_p^{p-q} \cdot \text{Resultant}(P, Q)$$

Through evaluation: Resultant (I)

$p, q \in \mathbb{P}_n$ with $n = \max(\deg(p), \deg(q))$.

$\tau = (\tau_1, \dots, \tau_{n+1}) \in \mathbb{C}^{n+1}$ and $\tilde{\tau} = (\tau_1, \dots, \tau_n) \in \mathbb{C}^n$.

$\mathbf{p} = (p_1, \dots, p_{n+1}) = (p(\tau_1), \dots, p(\tau_{n+1})).$

$\mathbf{q} = (q_1, \dots, q_{n+1}) = (q(\tau_1), \dots, q(\tau_{n+1})).$

$1 \leq i \leq n$: $p'_i = p'(\tau_i)$ and $q'_i = q'(\tau_i)$.

The Bezout matrix $\mathbf{Bez}_{p,q}$ in the Lagrange basis $\mathbf{L}(t; \tilde{\tau}) \in [\mathbb{P}_{n-1}]^n$ is the matrix:

$$\begin{bmatrix} p'_1 q_1 - p_1 q'_1 & \frac{p_1 q_2 - p_2 q_1}{\tau_1 - \tau_2} & \dots & \frac{p_1 q_n - p_n q_1}{\tau_1 - \tau_n} \\ \frac{p_2 q_1 - p_1 q_2}{\tau_2 - \tau_1} & p'_2 q_2 - p_2 q'_2 & \dots & \frac{p_2 q_n - p_n q_2}{\tau_2 - \tau_n} \\ \vdots & \vdots & & \vdots \\ \vdots & \vdots & & \vdots \\ \frac{p_n q_1 - p_1 q_n}{\tau_n - \tau_1} & \frac{p_n q_2 - p_2 q_n}{\tau_n - \tau_2} & \dots & p'_n q_n - p_n q'_n \end{bmatrix}$$

Through evaluation: Resultant (II)

Let $\{x_1, \dots, x_{p+q}\}$ be a set with $p + q$ elements

$$[p+q] = \{1, 2, \dots, p+q\}$$

$$\text{Res}(P, Q) = \sum_{\substack{I \subset_q [p+q], J \subset_p [p+q] \\ I \cup J = [p+q]}} \frac{\prod_{i \in I} P(x_i) \prod_{j \in J} Q(x_j)}{\prod_{i \in I, j \in J} (x_i - x_j)}$$

Advantages: no conditions on P or Q .

Disadvantages: exponential number of summands.

F. Apery, J.-P. Jouanolou: Élimination. Le cas d'une variable. Collection Méthodes. Hermann, 2006.

Through evaluation: Subresultants

Let $\{x_1, x_2, \dots, x_{p+q-t}\}$ be a set with $p + q - t$ elements.

$$E = \{1, 2, \dots, p + q - t\}$$

$$\mathbf{Sres}_t(P, Q) =$$

$$\sum_{\substack{I \subset_{q-t} E, J \subset_{p-t} E \\ K \subset_t E, I \uplus J \uplus K = E}} \frac{\prod_{i \in I} P(x_i) \prod_{j \in J} Q(x_j)}{\prod_{i \in I, j \in J} (x_i - x_j) \prod_{i \in I, k \in K} (x_i - x_k) \prod_{j \in J, k \in K} (x_j - x_k)} \prod_{k \in K} (x - x_k)$$

Advantages: no conditions on P and Q .

Disadvantages: exponential number of summands.

F. Apery, J.-P. Jouanolou: Élimination. Le cas d'une variable. Collection Méthodes.
Hermann, 2006.

RESULTANTS & SUBRESULTANTS THROUGH EVALUATION (OUR FORMULAE)

Through evaluation: Resultant

Let $\{x_1, \dots, x_{p+q}\}$ be a set with $p + q$ elements $[p + q] = \{1, 2, \dots, p + q\}$

$$\text{Res}(P, Q) = \frac{\begin{vmatrix} x_1^{q-1} P(x_1) & \dots & x_{p+q}^{q-1} P(x_{p+q}) \\ \vdots & & \vdots \\ P(x_1) & \dots & P(x_{p+q}) \\ x_1^{p-1} Q(x_1) & \dots & x_{p+q}^{p-1} Q(x_{p+q}) \\ \vdots & & \vdots \\ Q(x_1) & \dots & Q(x_{p+q}) \end{vmatrix}}{V(x_1, \dots, x_{p+q})}$$

Advantages:

- ✳ No conditions on P and Q .
- ✳ Derivatives of P and Q are not evaluated (but a bigger matrix).
- ✳ No exponential number of summands.

Through evaluation: Resultant (the proof)

$$\text{Res}(P, Q) = \begin{vmatrix} a_p & \dots & a_0 & & & \\ & \ddots & & \ddots & & \\ & & a_p & \dots & a_0 & \\ b_q & \dots & b_0 & & & \\ & \ddots & & \ddots & & \\ & & b_q & \dots & b_0 & \end{vmatrix} = \begin{vmatrix} a_p & \dots & \dots & \dots & \star & x^{q-1}P(x) \\ & \ddots & & & \vdots & \vdots \\ & & a_p & \dots & a_1 & P(x) \\ b_q & \dots & \dots & \dots & \star & x^{p-1}Q(x) \\ & \ddots & & & \vdots & \vdots \\ & & b_q & \dots & b_1 & Q(x) \end{vmatrix}.$$

Through evaluation: Resultant (the proof)

$$\text{Res}(P, Q) = \begin{vmatrix} a_p & \dots & a_0 \\ \ddots & & \ddots \\ b_q & \dots & b_0 \\ \ddots & & \ddots \\ b_q & \dots & b_0 \end{vmatrix} = \begin{vmatrix} a_p & \dots & \dots & \dots & \star & x^{q-1}P(x) \\ \ddots & & & & \vdots & \vdots \\ b_q & \dots & a_p & \dots & a_1 & P(x) \\ \ddots & & \ddots & & \vdots & \vdots \\ b_q & \dots & b_1 & & & Q(x) \end{vmatrix}.$$

$$\begin{vmatrix} x_1^{q-1}P(x_1) & \dots & x_{p+q}^{q-1}P(x_{p+q}) \\ \vdots & & \vdots \\ P(x_1) & \dots & P(x_{p+q}) \\ x_1^{p-1}Q(x_1) & \dots & x_{p+q}^{p-1}Q(x_{p+q}) \\ \vdots & & \vdots \\ Q(x_1) & \dots & Q(x_{p+q}) \end{vmatrix} = \begin{vmatrix} a_p & \dots & \dots & \dots & \star & x_{p+q}^{q-1}P(x_{p+q}) \\ \ddots & & & & \vdots & \vdots \\ b_q & \dots & a_p & \dots & a_1 & P(x_{p+q}) \\ \ddots & & \ddots & & \vdots & \vdots \\ b_q & \dots & b_1 & & & Q(x_{p+q}) \end{vmatrix}.$$

$$\cdot (x_1^{p+q-1}x_2^{p+q-2}\cdots x_{p+q-1}) + \text{l dt} = \text{Res}(P, Q) \cdot (x_1^{p+q-1}x_2^{p+q-2}\cdots x_{p+q-1}) + \text{l dt}$$

Through evaluation: Resultant (the proof)

$$\text{Res}(P, Q) = \begin{vmatrix} a_p & \dots & a_0 \\ \ddots & & \ddots \\ b_q & \dots & b_0 \\ \ddots & & \ddots \\ b_q & \dots & b_0 \end{vmatrix} = \begin{vmatrix} a_p & \dots & \dots & \dots & \star & x^{q-1}P(x) \\ \ddots & & & & \vdots & \vdots \\ b_q & \dots & a_p & \dots & a_1 & P(x) \\ \ddots & & \ddots & & \vdots & \vdots \\ b_q & \dots & b_1 & & & Q(x) \end{vmatrix}.$$

$$\begin{vmatrix} x_1^{q-1}P(x_1) & \dots & x_{p+q}^{q-1}P(x_{p+q}) \\ \vdots & & \vdots \\ P(x_1) & \dots & P(x_{p+q}) \\ x_1^{p-1}Q(x_1) & \dots & x_{p+q}^{p-1}Q(x_{p+q}) \\ \vdots & & \vdots \\ Q(x_1) & \dots & Q(x_{p+q}) \end{vmatrix} = \begin{vmatrix} a_p & \dots & \dots & \dots & \star & x_{p+q}^{q-1}P(x_{p+q}) \\ \ddots & & & & \vdots & \vdots \\ b_q & \dots & a_p & \dots & a_1 & P(x_{p+q}) \\ \ddots & & \ddots & & \vdots & \vdots \\ b_q & \dots & b_1 & & & Q(x_{p+q}) \end{vmatrix}.$$

$$\cdot (x_1^{p+q-1}x_2^{p+q-2}\cdots x_{p+q-1}) + \text{l dt} = \text{Res}(P, Q) \cdot (x_1^{p+q-1}x_2^{p+q-2}\cdots x_{p+q-1}) + \text{l dt}$$

Dividing this determinant by

$$V(x_1, \dots, x_{p+q}) = x_1^{p+q-1}x_2^{p+q-2}\cdots x_{p+q-1} + \text{lowest degree terms ,}$$

the corresponding degree comparison produces the searched equality.

Through evaluation: Subresultants

Let $\{x_1, x_2, \dots, x_{p+q-t}\}$ be a set with $p + q - t$ elements. $E = \{1, 2, \dots, p + q - t\}$

$$\beta_F(y_1, y_2, \dots, y_{p+q-2t}) = \frac{\begin{vmatrix} y_1^{q-t-1}P(y_1) & y_2^{q-t-1}P(y_2) & \dots & y_r^{q-t-1}P(y_r) \\ \vdots & \vdots & & \vdots \\ P(y_1) & P(y_2) & \dots & P(y_r) \\ y_1^{p-t-1}Q(y_1) & y_2^{p-t-1}Q(y_2) & \dots & y_r^{m-t-1}Q(y_r) \\ \vdots & \vdots & & \vdots \\ Q(y_1) & Q(y_2) & \dots & Q(y_r) \end{vmatrix}}{V(y_1, y_2, \dots, y_{p+q-2t})}$$

$$\text{Sres}_t(P, Q) = \sum_{\substack{[p+q-t] = I \uplus J \\ |I| = p+q-2t, |J| = t}} \beta_F((x_i)_{i \in I}) \cdot \frac{\prod_{j \in J} (x - x_j)}{\prod_{i \in I, j \in J} (x_i - x_j)}$$

Advantages: no conditions on P and Q .

Disadvantages: exponential number of summands (but smaller).

RESULTANTS & SUBRESULTANTS THROUGH EVALUATION (THE MOTIVATION)

The output of an algorithm may produce as solution an algebraic expression (a polynomial or a rational function) whose expansion:

- ➊ either is very costly, or
- ➋ produces a very complicated object to deal with,
- ➌ or requires a change of basis.

This happens, for example,

- ➊ when computing implicit equations for solving intersection problems in CAGD, or
- ➋ when numerically solving initial value problems for ordinary differential equations.

Algorithms for geometric entities (curves and surfaces) presented by polynomials given by values:

Symbolic Computation for polynomials presented, for example, “à la Lagrange” or “á la Hermite” when dealing with curves, surfaces,

Motivating Example

$$x(u, v) = 3v(v - 1)^2 + (u - 1)^3 + 3u$$

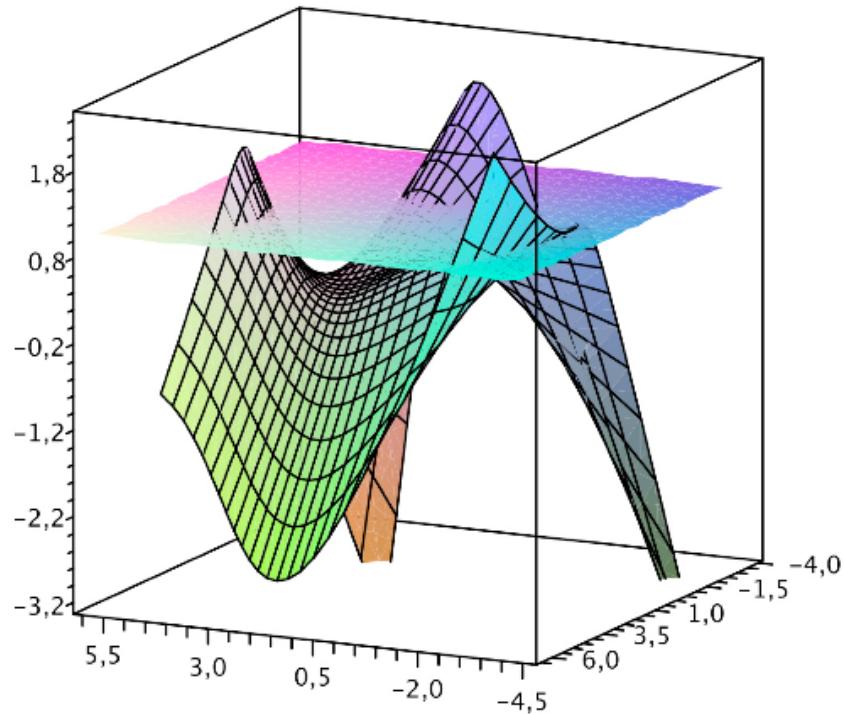
$$y(u, v) = 3u(u - 1)^2 + v^3 + 3v$$

$$\begin{aligned} z(u, v) &= -3u(u^2 - 5u + 5)v^3 - 3(u^3 + 6u^2 - 9u + 1)v^2 \\ &= +v(6u^3 + 9u^2 - 18u + 3) - 3u(u - 1). \end{aligned}$$

$$\begin{aligned} \mathbf{r}_1(x, y) &= -\frac{233469x}{2048} + \frac{188595y}{2048} - \frac{112832595}{262144} - \frac{81x^2}{64} \\ &\quad + \frac{135xy}{32} - \frac{81y^2}{64} \end{aligned}$$

$$\begin{aligned} \mathbf{r}_2(x, y) &= -\frac{20972672709381x}{536870912} + \frac{17975329363179y}{536870912} - \frac{729y^4}{8192} \\ &\quad - \frac{729x^4}{8192} + \frac{1215x^3y}{2048} + \frac{1215xy^3}{2048} - \frac{4105971x^3}{65536} \\ &\quad + \frac{3129597y^3}{65536} + \frac{14456151x^2y}{65536} - \frac{13181049xy^2}{65536} \\ &\quad + \frac{48101467761xy}{8388608} - \frac{38812918311y^2}{16777216} \\ &\quad - \frac{1}{2} \left(\frac{233469x}{2048} + \frac{112832595}{262144} + \frac{81x^2}{64} - \frac{188595y}{2048} \right. \\ &\quad \left. - \frac{135xy}{32} + \frac{81y^2}{64} \right) \left(-\frac{233469x}{2048} + \frac{188595y}{2048} + \frac{135xy}{32} \right. \\ &\quad \left. - \frac{81y^2}{64} - \frac{112832595}{262144} - \frac{81x^2}{64} \right) - \frac{4779x^2y^2}{4096} \\ &\quad - \frac{22656991982391171}{137438953472} - \frac{54187594407x^2}{16777216} + \dots \\ &= -\frac{20972672709381x}{536870912} + \frac{17975329363179y}{536870912} - \frac{729y^4}{8192} \\ &\quad - \frac{729x^4}{8192} + \frac{1215x^3y}{2048} + \frac{1215xy^3}{2048} - \frac{4105971x^3}{65536} \\ &\quad + \frac{3129597y^3}{65536} + \frac{14456151x^2y}{65536} - \frac{13181049xy^2}{65536} \\ &\quad + \frac{48101467761xy}{8388608} - \frac{38812918311y^2}{16777216} \\ &\quad - \frac{1}{2} \left(\frac{233469x}{2048} + \frac{112832595}{262144} + \frac{81x^2}{64} - \frac{188595y}{2048} \right. \\ &\quad \left. - \frac{135xy}{32} + \frac{81y^2}{64} \right) \cdot \boxed{\mathbf{r}_1(x, y)} - \frac{4779x^2y^2}{4096} \\ &\quad - \frac{22656991982391171}{137438953472} - \frac{54187594407x^2}{16777216} + \dots \end{aligned}$$

$$\mathcal{H}_{\mathcal{B}}(x, y, z) = z^9 + \sum_{i=1}^9 r_i(x, y) z^{9-i}$$



Motivating Example

$$\begin{aligned}f(x,y) &= 0 \\g(x,y) &= 0\end{aligned}$$

Coefficients not available directly

$$R(x) = \det(M(x)) = 0$$

Linearization: GEP
(without computing the determinant !)

Solving

$$f(\alpha, y) = 0$$

$$g(\alpha, y) = 0$$

with $R(\alpha) = 0$

Nullspace computations: SVD
Subresultants

G.-M. Diaz-Toca, M. Fioravanti, L. Gonzalez-Vega, A. Shakoori: *Using implicit equations of parametric curves and surfaces without computing them: Polynomial algebra by values*. Computer Aided Geometric Design 30, 116-139, 2013.

R. M. Corless, G.-M. Diaz-Toca, M. Fioravanti, L. Gonzalez-Vega, I. F. Rua, A. Shakoori: *Computing the topology of a real algebraic plane curve whose defining equations are available only "by values"*. Computer Aided Geometric Design 30, 675-706, 2013.

Motivating Example

$$\begin{aligned} u(t) - x &= 0 \\ v(t) - y &= 0 \end{aligned}$$

Coefficients of $u(t)$ and $v(t)$ not available directly

$$R(x,y) = \det(M(x,y)) = 0$$

Implicit equation in determinant form

Solving

$$R(w(s),z(s)) = 0$$

Generalized Eigenvalue Problem
(without computing the determinant !)

G.-M. Diaz-Toca, M. Fioravanti, L. Gonzalez-Vega, A. Shakoori: *Using implicit equations of parametric curves and surfaces without computing them: Polynomial algebra by values*. Computer Aided Geometric Design 30, 116-139, 2013.

R. M. Corless, G.-M. Diaz-Toca, M. Fioravanti, L. Gonzalez-Vega, I. F. Rua, A. Shakoori: *Computing the topology of a real algebraic plane curve whose defining equations are available only "by values"*. Computer Aided Geometric Design 30, 675-706, 2013.

RESULTANTS & SUBRESULTANTS THROUGH EVALUATION (CONCLUSIONS AND ...)

Conclusions and further work

Resultants and Subresultants through evaluation “à la Hermite

$$x_1 = x_2$$

$$\text{Res}(P, Q) = \frac{\begin{vmatrix} [x^{q-1}P(x)]'_{x=x_1} & x_1^{q-1}P(x_1) & x_3^{q-1}P(x_3) & \dots & x_{p+q}^{q-1}P(x_{p+q}) \\ \vdots & \vdots & \vdots & & \vdots \\ P'(x_1) & P(x_1) & P(x_3) & \dots & P(x_{p+q}) \\ [x^{p-1}Q(x)]'_{x=x_1} & x_1^{p-1}Q(x_1) & x_3^{p-1}Q(x_3) & \dots & x_{p+q}^{p-1}Q(x_{p+q}) \\ \vdots & \vdots & \vdots & & \vdots \\ Q'(x_1) & Q(x_1) & Q(x_3) & \dots & Q(x_{p+q}) \end{vmatrix}}{V(x_3, \dots, x_{p+q}) \prod_{k \geq 3} (x_1 - x_k)^2}$$

C. D'Andrea, T. Krick, A. Szanto: *Subresultants in multiple roots*. Linear Algebra and Its Applications 438, 1969-1989, 2013.

Conclusions and further work

Reducing the complexity of the expressions: replacing the exponential number of summands by a single determinant.

$$\deg(P) - \text{rank}(M(P, Q)) = \deg(\gcd(P, Q)).$$

Looking for a Barnett's factorization for $M(P, Q)$:

$$p_0^m \text{Bez}(P, Q) = \tilde{Q}(\Delta_P) \text{Bez}(P, 1) = \text{Bez}(P, 1) \tilde{Q}(\Delta_P^t).$$

GRACIAS
THANKS
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